

Manipulating industrial robots — Object handling with grasp-type grippers — Vocabulary and presentation of characteristics

The European Standard EN ISO 14539:2001 has the status of a British Standard

ICS 01.040.25; 25.040.30

National foreword

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Summary of pages

This document comprises a front cover, an inside front cover, the EN ISO title page, the EN ISO foreword page, the ISO title page, pages ii to viii, pages 1 to 32, the Annex ZA page and a back cover.

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